

SPECIFICATION  
FOR

PRE-STORED VECTOR INTERRUPT HANDLING  
SYSTEM AND METHOD

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Field of the Invention

[0001] The field of the present invention relates generally to processor-based systems, and, more particularly, to methods and systems for vectored interrupt handling in processor-based systems.

Background

[0002] Processor-based systems use peripheral components, also called input and output (I/O) devices, to communicate with the external environment. Perhaps the most familiar processor-based system is the digital computer. Examples of I/O devices found in computer systems include the keyboard, monitor, disk drive, modem, and network interface card, to name a few. An I/O device requiring attention usually sends an I/O service request of some sort to the processor.

[0003] In most applications, the speed and efficiency with which a system processes I/O requests is one of the chief determinants of the system's overall throughput. Thus, an ordinary single processor system generally must have some method for allocating the processor's time among each of the system's I/O devices as each one periodically requests attention from the processor. The predominant methods for servicing these requests are polling and interrupt control.

[0004] FIG. 1 is a block diagram functionally representing a processor-based system 100 using a polling method. Processor 101, RAM module 102, and ROM module 103, and possibly other system components not shown in the diagram, are each connected to a system bus 104. A plurality of I/O devices 107 are also connected to the system bus 104. Each I/O device 107 is also connected to the inputs of a processor-controlled multiplexer 106, which is selectively controlled by the processor 101 by a select signal 115. In a typical application of the polling method, the multiplexer 106 is responsible for querying (i.e., polling) each I/O device 107, in turn, to determine whether the I/O device 107 needs the attention of the processor 101. If the I/O device being polled requires the attention of the processor 101, as indicated by the state of multiplexer output signal 120, the processor 101 responds by suspending its current operation and devoting its time to servicing the I/O device 107 in need. If the I/O device 107 being polled is not currently in need of service, the multiplexer 106 will poll the next I/O device 107 in sequence until all the I/O devices 107 have been queried. The processor 101 loops continuously through the polling cycle, temporarily suspending program execution whenever the polling cycle encounters an I/O device 107 in need of service.

[0005] FIG. 2 is a block diagram functionally representing an interrupt control method of processing I/O service requests. Processor 201, RAM module 202, and ROM module 203, and possibly other system components not shown in the diagram, are each connected to a system bus 204. A plurality of I/O devices 207 are also connected to the system bus 204. The interrupt control method in certain applications generally facilitates service requests by aggregating interrupt request ("IRQ") lines in a

control block conventionally known as a programmable interrupt controller (PIC) **206**. The PIC **206** is responsible for overall management of the interrupt process. As a practical matter, I/O devices **207** almost never assert interrupt signals directly to the processor **201**. Instead, the PIC **206** centralizes control and determines whether the  
5 current interrupt request is of greater importance than the current processor task. This determination is called prioritization and is usually performed by a prioritizer within the PIC.

**[0006]** Prioritization is a means of hierarchically arranging the order of interrupt handling by the processor when more than one I/O device requests service either  
10 simultaneously or sequentially. Systems establish priority through either hardware or software. Some computer systems establish hardware priority by the physical placement of I/O device interfaces along the backplane. Thus, a device's physical placement on the backplane corresponds to its level in the hierarchy. For instance, I/O devices of higher priority sit physically closer to the processor while I/O devices of lower  
15 priority are placed near the end of the device chain, further out on the backplane.

**[0007]** In addition to prioritization, the PIC masks the issuance of interrupt signals to the processor. Masking is utilized to dynamically control which interrupts are serviceable. For those applications where interruption would be undesirable, service requests may be temporarily disabled. However, some interrupts are non-maskable,  
20 such as power failure. In some systems, a service request that is issued while interrupts are disabled may be saved for processing after interrupts become re-enabled.

**[0008]** Turning once again to the example of a conventional system as shown in **FIG. 2**, after masking and establishing priority, the PIC **206** asserts an interrupt signal to

the processor's IRQ input. The processor **201** responds to the request by performing an interrupt service routine (ISR), sometimes called an interrupt handler program, which has been pre-loaded in memory **202, 203**. The processor "fulfills" an interrupt request by completing the ISR associated with the particular I/O device **207**.

5 **[0009]** A common implementation of the interrupt control method involves a "vectored" interrupt, which allows the processor to know which device issued the interrupt request. In this context, the vector is an address, or pointer, to the corresponding ISR. When the processor receives an IRQ from the PIC, the processor searches memory for the vector that corresponds to the branch instruction associated  
10 with the ISR for the particular device.

**[0010]** With both polling and interrupt control techniques, the processor must temporarily suspend execution of the current program in order to execute the ISR. The processor first completes the current program instruction, then saves the current state of the register bank, including the program counter (PC), to a stack location in memory  
15 known as the process control block. At the completion of the ISR, the register and PC values are restored from the process control block and program execution continues with the instruction located at the memory address originally held by the PC prior to the interrupt. In this way, the processor is able to satisfy the aforementioned need for allocating its time among several I/O devices.

20 **[0011]** Both polling and interrupt control techniques employ the processor to seek out the interrupt source. Each method is inefficient and wasteful in its own regard. The polling method wastes processor time looping through the polling cycle to the potentially serious detriment of system throughput. The interrupt control method typically uses an

inefficient software search process for identifying the interrupt source that often involves reading interrupt data (e.g. flags or data registers) from the PIC and parsing the data provided. In both methods, the overhead of parsing the data provided by the PIC increases as more interrupt sources are added to a system. Once the source is  
5 determined, the processor finally branches to the ISR and the ISR is executed.

**[0012]** The software search routine employed by the interrupt control method introduces unnecessary delay between the assertion of an interrupt and the start of the execution of the appropriate ISR. This delay can become particularly pronounced in systems that have dozens or hundreds of interrupts. For some real-time systems, notably the digital signal processors found in wireless telephones, this latency represents a substantial burden to efficient signal processing. It would therefore be advantageous to provide a faster, more efficient technique for servicing multiple I/O devices or other components requiring service in a processor-based system.

### Summary of the Invention

15 **[0013]** The invention is directed in one respect, to a system and method for handling interrupts in processor-based systems. In a preferred embodiment, processor branch instructions are stored as vectors in a vector store, with each of the vectors corresponding to an interrupt service routine in memory. When an event occurs, the pre-stored vector interrupt handling system loads the execution unit with a vector from  
20 the vector store, rather than an instruction from memory, whenever the processor undergoes an instruction fetch cycle in response to an IRQ input. The processor then

immediately effectively branches to the location specified by the vector and performs the corresponding interrupt service routine.

[0014] Direct vector delivery affords the system reduced interrupt-processing latency by avoiding software intensive search routines. In processor-based systems involving large numbers of interrupts, the overhead savings realized by the pre-stored vector interrupt handling system can be substantial. In the context of this invention, an interrupt vector comprises a complete branch instruction, which includes the branch op-code and the target address.

#### **Brief Description of the Drawings**

[0015] FIG. 1 is a block diagram illustrating a processor-based system using a polling method of processing interrupts.

[0016] FIG. 2 is a block diagram illustrating a processor-based system using an interrupt method of processing interrupts.

[0017] FIG. 3 is a block diagram of a pre-stored vector interrupt handling system using a selector in accordance with one embodiment as disclosed herein.

[0018] FIG. 4 is a block diagram of a multi-channel pre-stored vector interrupt handling system using a prioritizer in accordance with another embodiment as disclosed herein.

[0019] FIG. 5 is a flow diagram illustrating steps of a method for processing interrupts according to one embodiment as disclosed herein.

**Detailed Description of Preferred Embodiments**

**[0020]** FIG. 3 is a block diagram of one embodiment of a pre-stored vector interrupt handling system. As shown in FIG. 3, a plurality of I/O devices 301 are connected to an interrupt control device 303 via a plurality of interrupt request lines 302.

5 The interrupt control device 303 outputs a master interrupt request signal 330 connected to the interrupt request (IRQ) input 310 of a processor 304. The processor 304, along with a program store 305 and interrupt vector store 308 (and potentially other components not illustrated in FIG. 3), are connected to a system bus 306. A control signal 311 is output from the processor 304 to an address decoder and selector 307, which is connected to the program store 305 via a chip select (CS) control signal 335 and the interrupt vector store 308 via a CS\_irq control signal 336. The address decoder and selector 307 is also coupled to the system bus 306 by signal path 340. The interrupt control device 303 is also connected to the interrupt vector store 308, via an interrupt identification signal 309.

15 **[0021]** In operation, when service is requested by one of the I/O devices 301, the interrupt control device responds by (1) issuing an interrupt identifier 309 to the interrupt vector store 308, and (2) asserting a master interrupt request signal 330 to the IRQ input 310 of the processor 304. In response to the master IRQ signal 330, the processor 304 issues a control signal (also referred to herein as a C\_type, or cycle type signal) 311, that corresponds to a specific bus cycle type. Specific implementations of cycle type signaling are processor dependent. For example, in one embodiment, the cycle type signals are codes which are interpreted to correspond to the various cycle type operations (i.e., data write, data read, instruction fetch, etc.) supported by the

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particular processor. The address decoder and selector **307** is responsible for intercepting the processor's cycle type signal. When (1) the cycle type signal that the address decoder and selector **307** intercepts is qualified by the address decoder and selector **307** to be an instruction fetch operation, and (2) the address on the address bus resolves to a valid memory mapped location in the program store associated with the interrupt vector store, the address decoder and selector **307** asserts a control signal **336** to the interrupt vector store **308**. The address decoder and selector **307** (which could in some instances be embodied as simply as a flip-flop having inverting and non-inverting outputs) does this by de-asserting the chip select signal **335** for the program store **305** and instead asserting the interrupt request chip select (CS\_Irq) signal **336** to the interrupt vector store **308**. The CS\_Irq signal **336** and the chip select signal **335** are mutually exclusive. The interrupt vector store **308** then delivers a pre-stored vector (in the form of a branch instruction op-code and address) directly to the processor's execution unit **315**. The processor immediately executes the branch instruction and inserts the address into the program counter, rather than allowing the processor **304** to fetch the branch instruction from the program store **305**, as is conventionally done. The processor **304**, program store **305**, address decoder and selector **307**, and interrupt vector store **308** blocks in the diagram, by virtue of being connected together by a system bus **306**, are permitted to perform addressing and data transfer between them. However, the address decoder and selector **307** is given read-only access to the address portion of the system bus **306**, while the interrupt vector store **308** is allowed only write access to the data portion of the bus **306**.



[0022] The execution unit of the processor often includes an instruction fetcher, an instruction decoder, an arithmetic/logic unit (ALU), a program counter, and potentially other components depending upon the complexity of the processor. In one embodiment of the pre-stored vector interrupt handling system, the branch instruction op-code and address are delivered to the processor's execution unit **315** by the interrupt vector store **308**. Under this embodiment the execution unit is responsible for decoding the branch instruction op-code and delivering the branch instruction address to the execution unit's program counter. The next instruction is then fetched from the branch address location. However, another embodiment of the pre-stored interrupt vector handling system contemplates delivery of the address component of the branch instruction to the program counter of the execution unit **315** directly from the interrupt vector store **308**, bypassing the execution unit's instruction fetch and decode logic. This embodiment is advantageous because instruction execution delay is minimized, but implementation of this embodiment would require programmer access to the internal workings of the processor. Thus, the embodiment one chooses to implement for a specific application of the pre-stored vector interrupt handling system is processor-dependent.

[0023] The pre-stored vector interrupt handling system **300** may also include a mechanism for masking the interrupt request lines **302**. Masking is used to temporarily disable one or more interrupt request lines **302** when an application under processor control would be negatively affected if the application were interrupted. Including an interrupt mask register (not shown) within the interrupt control device **303** represents one way to enable interrupt masking. In such a case, the interrupt control device **303**

would be connected to the system bus 306, enabling the processor 304 to adjust the contents of the interrupt mask register.

[0024] Another embodiment of a pre-stored vector interrupt handling system incorporating one or more concepts of the system of FIG. 3 includes a prioritizer within the interrupt control element. With a prioritizer, a plurality of interrupt request signals entering the interrupt control device can be prioritized prior to processing. Additionally, the prioritizer may be configured to assert an interrupt identifier signal to the interrupt vector store for identifying which interrupt vector to drive out when the pre-stored vector interrupt handling system intercepts the processor's normal instruction fetch cycle type signal. Prioritization can be particularly useful in two situations: (1) when more than one I/O device requests service at the same time, or (2) when an I/O device issues a more urgent (higher priority) request than the urgency of the interrupt request of lower priority currently being processed. In the second situation, the interrupt request of lower priority is said to be nested within the interrupt request of higher priority. The handling of nested interrupts is processor dependent. Thus, while a prioritizer may have no trouble issuing multiple concurrent (i.e., nested) interrupts of varying priority, each processor is designed or configured to receive and handle these nested interrupts in different ways. Alternatively, some processors may disallow nested or prioritized interrupt handling altogether by masking out subsequent interrupt request signals from the prioritizer once processing of an earlier interrupt request has begun.

[0025] The pre-stored vector interrupt handling system is processor independent. Yet, many microprocessors contain elements, such as cache RAM, which may require a change in the pre-stored vector interrupt handling system's operations. The pre-stored

vector interrupt handling circuitry should be positioned so that interrupt vectors do not get stored in the instruction cache. For example, if the processor **304** of **FIG. 3** contains a cache element, the contents of the cache may need to be saved by the processor **304** in addition to saving the register bank and program counter. Additionally, the processor **304** may use pipelining techniques to pre-fetch instructions from the program store **305**. When pipelining or burst fill techniques are used by a processor, the interrupt vector store should hold sufficient instructions to meet the processor's specific requirements. In both cases, the pre-stored vector interrupt handling system relies on the processor to manage caching and instruction pre-fetch capabilities, potentially requiring a slight modification to **FIG. 3**.

**[0026]** **FIG. 4** is a block diagram of a multi-channel pre-stored vector interrupt handling system **400** using a prioritizer **403** as part of an interrupt controller **450**. In **FIG. 4**, separate data bus **408** and address bus **407** portions of the system bus are depicted. A processor **409** and program store **429** are connected to both the data bus **408** and the address bus **407**. An interrupt vector store **406** is connected to the data bus **408**. An address decoder **405**, which is part of a selector **470**, is connected to the address bus, for accepting the high order (p-n) bits from the address bus for use in resolving the contents of the address bus with the memory mapped location associated with the interrupt vector store **406**. The address bus **407** is further connected to a multiplexer **404** via bus channel **427**. The multiplexer **404** assists in switching the system **400** between normal interrupt handling operation (interrupt mode) and vector store initialization (initialization mode), as further described below. A selector **470** is connected to the interrupt vector store **406** and issues a mode control signal **428** to the

read/write (R/W) input of the interrupt vector store **406**. The selector is further connected to the CS\_VS input of the interrupt vector store **406** by a control signal **451** and to the CS\_PS input of the program store **429** by a control signal **440**. A plurality of up to  $2^n$  I/O devices **401** are connected to the prioritizer **403** via a plurality of up to  $2^n$  interrupt request lines **402**. The prioritizer **403** outputs a multi-bit prioritized interrupt source identifier signal **410** of  $n$  bits unambiguously identifying the interrupt source to the multiplexer **404**. The relationship between the number of serviceable I/O devices **401** and the corresponding preferred bit width of the interrupt source identifier signal **410** is given by  $n = \log_2 m$ , where  $m$  represents the maximum number of serviceable I/O devices, and  $n$  represents the size of the interrupt source identifier signal **410** in bits, rounded upwards. For example, for up to 32 I/O devices **401**,  $n$  would be 5; for up to 16 I/O devices **401**,  $n$  would equal 4.

[0027] The selector's address decode block **405** preferably exists independently of any other address decoder functionality which may be present in the system **400** or external thereto. Modified chip select logic external to the pre-stored vector interrupt handling system is also preferably provided to signal when the system operates in initialization mode. For example, a set of registers within the processor **409**, which defines the processor's current state, may supply a control signal to the selector **470** for this purpose. This may be simply a status register or flag which the pre-stored vector interrupt handling system **400** can rely on to provide notification of the start of initialization. Similar external logic is responsible for ensuring that no other devices are selected for the data bus **408** at the same time the interrupt vector is being loaded thereon.

[0028] During vector store initialization (initialization mode), the CS\_VS input to the interrupt vector store 406 is activated by control signal 451 to give the interrupt vector store exclusive control of the data bus. The selector must also ensure during initialization that the CS\_Code control signal to the CS\_PS input of the program store 429 is deselected. As part of initialization mode operation, the address decoder and selector 470 also (1) issues control signal 428 to the interrupt vector store 406 placing the interrupt vector store 406 in a write (W) mode, and (2) issues mode control signal 428 to the multiplexer 404 forcing the multiplexer 404 into an initialization mode. Upon successfully resolving the address bus high bits (p-n) to the memory mapped location of the interrupt vector store, the multiplexer 404 will transparently pass the address bus 407 low bits (n) to the interrupt vector store 406 via bus channel 427.

[0029] While in initialization mode, the address bus 407 receives the memory address corresponding to a specific interrupt vector (in the form of a branch instruction address) for a particular interrupt service routine. Also while in initialization mode, the data bus 408 receives the specific interrupt vector (i.e., branch instruction op-code and address) waiting to be written to the interrupt vector store 406. The system 400 cycles through all of the interrupt vectors and their allocated addresses to load the interrupt vector store 408. Loading can be carried out under the control of the processor 409 or another controller (e.g., a DMA controller). Initialization is complete when the interrupt vector store 408 holds a copy of every interrupt service routine branch instruction.

[0030] The inclusion of a multiplexer 404 as a component of the pre-stored vector interrupt handling system is necessary only insofar as no other method of interrupt vector store 406 initialization exists. One embodiment of the pre-stored vector interrupt

handling system contemplates the implementation of the interrupt vector store **406** in ROM (not shown in FIG. 3 or FIG. 4). In this case, no multiplexer **404** would be required. Certain of the chip select logic and address decoding functionality would have to be modified accordingly to accommodate the absence of a multiplexer.

5 [0031] When the pre-stored vector interrupt handling system **400** finishes initializing the interrupt vector store **406**, the system **400** switches to an operational mode (interrupt mode). While in interrupt mode, the selector **470** (1) issues a mode control signal **428** to the multiplexer **404**, forcing the multiplexer **404** into interrupt mode (so that it will henceforth pass through the interrupt source identifier **410** from the prioritizer **403** rather than the address bus **407**), and (2) issues the mode control signal **428** to the interrupt vector store **406**, forcing the interrupt vector store **406** into a read (R) mode. During interrupt mode, information is normally only read from, not written into, the interrupt vector store **406**, unless for some reason the interrupt vectors are modified during running of the program.

15 [0032] In both initialization and interrupt modes, the selector **470** is responsible (as between the interrupt vector store **406** and the program store **429** devices only) for ensuring exclusive access to the data bus **408** by one or the other of the two devices. In one embodiment, the selector uses simple digital logic using AND, OR, or NOT gates to deliver the CS\_PS and CS\_VS signals to the interrupt vector store **406** or the  
20 program store **429**. Thus, when the CS\_VS input to the interrupt vector store is asserted via control signal **451**, the selector ensures that the CS\_PS input to the program store **429** via control signal **440** is deasserted. Likewise, when the CS\_PS input to the program store **429** is asserted via control signal **440**, the selector ensures

that the CS\_VS input to the interrupt vector store **406** is deasserted. In this manner, the interrupt vector store and the program store will not control the data bus simultaneously.

**[0033]** The separate R/W control signal **428** and CS\_VS control signal **451** inputs to the interrupt vector store **406** are both necessary in this embodiment of the pre-stored vector interrupt handling system. The R/W control signal input to the interrupt vector store **406** ensures that the interrupt vector store **406** remains asserted write (W) throughout the initialization mode, and read (R) throughout the interrupt mode. The separate CS\_VS input to the interrupt vector store **406** ensures that the interrupt vector store **406** maintains exclusive control of the data bus **408** in both the interrupt mode and the initialization mode.

**[0034]** In interrupt mode, in the absence of any interrupt, the processor **409** reads out and executes instructions from the program store **429**. During this time, the processor's cycle type output signal **435**, which is connected to the selector **470**, is kept in a state indicating that the processor **409** is operating in a non-interrupt situation.

When no interrupts are present, the selector **470** keeps the chip select signal **440** to the program store **429** asserted, and the interrupt request chip select signal **451** to the interrupt vector store **406** de-asserted.

**[0035]** The prioritizer **403** from time to time will receive interrupt requests from I/O devices **401** via the plurality of interrupt request lines **402**. When an interrupt occurs during the interrupt mode, the master interrupt request signal **436** is asserted from the prioritizer **403** to the processor **409**, which, in response, finishes its current instruction and asserts the cycle type signal **435**, and the R/W signal **444**, both connected to the selector **470**. The selector **470**, as before (with the embodiment shown in FIG. 3),

intercepts the processor's instruction fetch cycle type signal, as well as the processor's R/W output signal and address, and causes an interrupt vector (branch instruction op-code and address) to be directly loaded into the processor **409**, by de-selecting the program store **429** and selecting the interrupt vector store **406**. The prioritizer **403**, in addition to generating the master interrupt request signal **436**, identifies the appropriate vector by generating an interrupt identifier signal **410** based upon the interrupt that occurred (or, if multiple interrupts, the highest priority interrupt). The interrupt identifier signal **410** is passed through the multiplexer **404** to the interrupt vector store **406**, forcing the corresponding interrupt vector from the interrupt vector store **406** onto the data bus **408**. More specifically, the selector **470** selects the interrupt vector store **406**, making its contents available on the data bus **408**. When the processor **409** asserts the cycle type signal **435**, it expects an interrupt vector (branch instruction op-code and address) to follow, and the interrupt vector from the data bus **408** is therefore loaded directly into the execution unit **452** of the processor **409**.

**[0036]** A feature with both the systems in **FIGS. 3** and **4** is that the interrupt identifier signal essentially provides a multi-bit encoded identification of the interrupt source and, hence, of the interrupt vector. The interrupt identifier signal can, in various embodiments, be applied directly to the interrupt vector store **308** or **406** as the address at which the corresponding interrupt vector is to be found. This direct correspondence between interrupt identifier and location of interrupt vector in the interrupt vector store provides advantages of speed and efficiency when responding to interrupts.

**[0037]** As with the system **300** described with respect to **FIG. 3**, the system **400** of **FIG. 4** may include circuitry for masking various interrupt sources. For example,



interrupt mask registers can be used to hold individual mask bits each indicating whether or not a specific interrupt may pass through. Each mask bit may control a gate (e.g., an AND gate or NAND gate) which allows the corresponding interrupt signal to pass through depending upon the state of the mask bit. Masking may be nested or  
5 unnested. If nested, higher-tier mask bits may each control a designated group of lower-tier mask bits. Interrupts only pass through if both the lower-tier mask bit specific to the interrupt and the higher-tier mask bit for the interrupt's designated group are both set appropriately.

**[0038]** FIG. 5 depicts a flow diagram of the steps followed by a processor-based system incorporating a pre-stored vector interrupt handling system, such as, for example, the system in FIG. 3 or FIG. 4. In a first step 505, program code for the application is loaded into a program store (memory). In a next step 510, the pre-stored vector interrupt handling system is initialized using, as one example, the initialization technique described in the example embodiment description of FIG. 4. Step 510 is an  
15 optional step if the interrupt vector store is implemented in ROM. In step 515, program execution begins. Program execution is portrayed in FIG. 5 by the series of program instruction blocks labeled "Program instruction 1", 520 "Program instruction 2", 525 through "Program instruction N", 585. During normal program execution, the processor's instruction cycle is interrupted when the pre-stored vector interrupt handling  
20 system receives an unmasked service request from the interrupt controller 530.

**[0039]** In step 535 the interrupt controller prioritizes the interrupt before asserting an interrupt request signal (IRQ) to the processor 540. Processing the interrupt first may require a stack dump of the registers and the program counter to a stack. The

interrupt controller intercepts the processor's instruction fetch bus cycle operation in step 550 by selecting the interrupt vector store and deselecting the program store. In step 555, the branch instruction op-code and address (interrupt vector) corresponding to the interrupt controller's identifier signal, travels directly to the processor's execution unit

5 560. After the execution of the interrupt vector 565, the next instruction executed by the processor will be the first instruction of the requested interrupt service routine 570. At the completion of the interrupt service routine in step 570, the saved contents of the PC and registers are retrieved from the stack and program execution resumes at the point where the processor instruction cycle was interrupted 580.

10 [0040] In each embodiment of the claimed invention, the interrupt sources can be either data storage devices, such as hard disk drives; data output devices, such as video display monitors; embedded hardware devices, such as timers; or data input devices, such as a keypad or a pointing device. Each of these categories of I/O devices is capable of benefiting from the advantages derived by the pre-stored vector interrupt

15 handling system. The claimed invention and its embodiments act independently of the nature and number of interrupt sources.

20 [0041] While the embodiments of the pre-stored interrupt vector handling system described herein all use a cycle type (C\_type) signal to qualify the processor's current bus cycle, the use of such a signal is not a pre-requisite of the invention. Cycle type signals are commonly found on processors and ease bus cycle decoding. One skilled in the art will realize that the address decoders and selectors shown in FIG. 3 and FIG. 4 may need modification for use with processors that do not produce cycle type signals. These modifications will be processor specific.

[0042] Moreover, a person skilled in the art will know that a processor-based system is broad enough to include a computer system, a wireless communication device such as a cell phone, a microcontroller, a digital signal processing system, or any interrupt-driven system which includes a central processor. A processor according to the various embodiments described herein may, for example, be a general purpose processor, an application-specific processor, a digital signal processor (DSP), or any other type of processor that is used to process instructions.

[0043] Various embodiments as described herein are expected to be faster than conventional interrupt methods for the following reasons: First, the pre-stored vector interrupt handling system is faster than traditional methods of interrupt handling because the system is not delayed by time-consuming searches that the traditional methods used for locating an interrupt service routine in memory. Second, interrupt latency can be low because the pre-stored vector interrupt handling system is completely implemented in hardware, while the traditional methods of searching for the location of an interrupt service routine are generally software-based. Third, processor time is not wasted searching for the interrupt service routine because the pre-stored vector interrupt handling system delivers a vector (branch instruction op-code and address) from the interrupt vector store directly to the processor's execution unit. As a result, the very next instruction the processor executes will be the first instruction of the relevant interrupt service routine.

[0044] The pre-stored vector interrupt handling system offers additional advantages, including processor independence, scalability, and nesting. Because the pre-stored vector interrupt handling system operates independently of specific

processor instruction sets, the system may be used with many different processors. Furthermore, the system is scalable to any number of interrupt request sources. In a pre-stored vector interrupt handling system design that incorporates a prioritizer, such as, for example, the system of **FIG. 4**, interrupt nesting is possible by suitably  
5 configuring the prioritizer.

**[0045]** While various embodiments have been described herein in which various components are described as being connected to one another, it should be noted that the term "connected" is used in its broadest sense to mean connected directly or indirectly. For example, those skilled in the art will appreciate that various signals may be routed through multiplexers, buffers or other intermediate components, without changing the general overall functionality of the various systems, processes and apparatuses described herein. Therefore, the addition of other elements or components to the various implementations of the interrupt handling systems and processes described herein is intended to be fully encompassed within the scope of the invention.

15 **[0046]** While preferred embodiments of the invention have been described herein, many variations are possible which remain within the concept and scope of the invention. Such variations would become clear to one of ordinary skill in the art after inspection of the specification and the drawings. The invention therefore is not to be restricted except within the spirit and scope of any appended claims.